

Solution to Suggested Problems - Sec 6.1, 7.1-7.2
Math 81

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• Section 6.1: 3, 13, 22

• Section 7.1: 1, 3

• Section 7.2: 3, 6, 16, 25

• Section 6.1

3. $A = \begin{pmatrix} 8 & -6 \\ 3 & -1 \end{pmatrix}$

Eigenvalues: $0 = \det(A - \lambda I)$
 $= \det\left(\begin{pmatrix} 8 & -6 \\ 3 & -1 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) = \det\begin{pmatrix} 8-\lambda & -6 \\ 3 & -1-\lambda \end{pmatrix}$
 $= \begin{vmatrix} 8-\lambda & -6 \\ 3 & -1-\lambda \end{vmatrix} = (8-\lambda)(-1-\lambda) + 18$
 $= \lambda^2 - 7\lambda + 10$
 $= (\lambda - 2)(\lambda - 5)$

$\lambda_1 = 2, \lambda_2 = 5$

• Eigenvectors:

$\lambda_1 = 2$ Solve $(A - \lambda_1 I)\vec{v} = \vec{0}$
 $\begin{pmatrix} 8-2 & -6 \\ 3 & -1-2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 6 & -6 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$\begin{pmatrix} 6 & -6 \\ 3 & -3 \end{pmatrix} \xrightarrow{\frac{1}{6}r_1} \begin{pmatrix} 1 & -1 \\ 3 & -3 \end{pmatrix} \xrightarrow{r_2 \rightarrow r_2 - 3r_1} \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}$ v_2 arbitrary, so let $v_2 = t$
 $v_1 - v_2 = 0 \rightarrow v_1 = t$

$\vec{v} = \begin{pmatrix} t \\ t \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

So $\lambda_1 = 2, \vec{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\lambda_2 = 5$ Solve $(A - \lambda_2 I)\vec{v} = \vec{0}$

$\begin{pmatrix} 3 & -6 \\ 3 & -6 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 3 & -6 \\ 3 & -6 \end{pmatrix} \xrightarrow{r_1 \rightarrow \frac{1}{3}r_1} \begin{pmatrix} 1 & -2 \\ 3 & -6 \end{pmatrix} \xrightarrow{r_2 \rightarrow r_2 - 3r_1} \begin{pmatrix} 1 & -2 \\ 0 & 0 \end{pmatrix}$

v_2 arbitrary so let $v_2 = t$
 $v_1 - 2v_2 = 0 \rightarrow v_1 = 2t \Rightarrow \vec{v} = \begin{pmatrix} 2t \\ t \\ t \end{pmatrix} = t \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$
 So $\lambda_2 = 5, \vec{v} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$

13. $A = \begin{pmatrix} 2 & 0 & 0 \\ 2 & -2 & -1 \\ -2 & 6 & 3 \end{pmatrix}$

Eigenvalues: $0 = \det(A - \lambda I)$
 $= \begin{vmatrix} 2-\lambda & 0 & 0 \\ 2 & -2-\lambda & -1 \\ -2 & 6 & 3-\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} -2-\lambda & -1 \\ 6 & 3-\lambda \end{vmatrix}$
 $= (2-\lambda)[(-2-\lambda)(3-\lambda) + 6]$
 $= (2-\lambda)[\lambda^2 - 1]$
 $= \lambda(1-\lambda)(2-\lambda) \Rightarrow \lambda_1 = 0, \lambda_2 = 1, \lambda_3 = 2$

Eigenvectors:

$\lambda_1 = 0$ | Solve $A\vec{v} = \vec{0}$

$$\begin{pmatrix} 2 & 0 & 0 \\ 2 & -2 & -1 \\ -2 & 6 & 3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 0 & 0 \\ 2 & -2 & -1 \\ -2 & 6 & 3 \end{pmatrix} \xrightarrow{\substack{r_2 \rightarrow r_2 - r_1 \\ r_3 \rightarrow r_3 + r_1}} \begin{pmatrix} 2 & 0 & 0 \\ 0 & -2 & -1 \\ 0 & 6 & 3 \end{pmatrix} \xrightarrow{r_3 \rightarrow r_3 + 3r_2} \begin{pmatrix} 2 & 0 & 0 \\ 0 & -2 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$\Rightarrow v_3$ arbitrary + $2v_1 = 0 \Rightarrow v_1 = 0$
 $-2v_2 - v_3 = 0 \Rightarrow v_2 = -\frac{1}{2}v_3$

Let $v_3 = 2t \Rightarrow v_2 = -t$
 So $\vec{v} = \begin{pmatrix} 0 \\ -t \\ 2t \end{pmatrix} = t \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix} \Rightarrow \lambda_1 = 0, \vec{v} = \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}$

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$\lambda_2=1$ | Solve $(A-I)\vec{v}=\vec{0}$

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & -1 \\ -2 & 6 & 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & -1 \\ -2 & 6 & 2 \end{pmatrix} \xrightarrow{\substack{r_2 \rightarrow r_2 - 2r_1 \\ r_3 \rightarrow r_3 + 2r_1}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & 6 & 2 \end{pmatrix} \xrightarrow{r_3 \rightarrow r_3 + 2r_2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$\Rightarrow v_1 = 0$
 $-3v_2 - v_3 = 0 \Rightarrow v_2 = -\frac{1}{3}v_3$
 v_3 arbitrary, so let $v_3 = 3t$
 $\Rightarrow v_2 = -t$

So $\vec{v} = \begin{pmatrix} 0 \\ -t \\ 3t \end{pmatrix} = t \begin{pmatrix} 0 \\ -1 \\ 3 \end{pmatrix} \Rightarrow \lambda_2=1, \vec{v} = \begin{pmatrix} 0 \\ -1 \\ 3 \end{pmatrix}$

$\lambda_3=2$ | Solve $(A-2I)\vec{v}=\vec{0}$

$$\begin{pmatrix} 0 & 0 & 0 \\ 2 & -4 & -1 \\ -2 & 6 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & 0 \\ 2 & -4 & -1 \\ -2 & 6 & 1 \end{pmatrix} \xrightarrow{r_1 \leftrightarrow r_3} \begin{pmatrix} -2 & 6 & 1 \\ 2 & -4 & -1 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{r_2 \rightarrow r_2 + r_1} \begin{pmatrix} -2 & 6 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$-2v_1 + 6v_2 + v_3 = 0$
 $2v_2 = 0 \rightarrow v_2 = 0$
 $\Rightarrow v_1 = \frac{1}{2}v_3$

v_3 arbitrary, so let $v_3 = 2t \Rightarrow v_1 = t$

So $\vec{v} = \begin{pmatrix} t \\ 0 \\ 2t \end{pmatrix} = t \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \Rightarrow \lambda_3=2, \vec{v} = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$

over \Rightarrow

$$22. A = \begin{pmatrix} 5 & -6 & 3 \\ 6 & -7 & 3 \\ 6 & -6 & 2 \end{pmatrix}$$

Eigenvalues: $0 = \det(A - \lambda I)$

$$\begin{aligned}
 &= \begin{vmatrix} 5-\lambda & -6 & 3 \\ 6 & -7-\lambda & 3 \\ 6 & -6 & 2-\lambda \end{vmatrix} = \begin{vmatrix} 5-\lambda & -6 \\ 6 & -7-\lambda \end{vmatrix} \cdot \begin{vmatrix} 5-\lambda & -6 \\ 6 & -6 \end{vmatrix} \\
 &= (5-\lambda)(-7-\lambda)(2-\lambda) - 108 - 108 \\
 &\quad - 6(-7-\lambda)(3) + 18(5-\lambda) + 36(2-\lambda) \\
 &= (5-\lambda)(-7-\lambda)(2-\lambda) - 216 - 18(-7-\lambda) + 18(5-\lambda) \\
 &\quad + 36(2-\lambda) \\
 &= (5-\lambda)(\lambda^2 + 5\lambda - 14) - 216 + 126 + 18\lambda + 90 - 18\lambda \\
 &\quad + 72 - 36\lambda \\
 &= -\lambda^3 + 39\lambda - 70 + 72 - 36\lambda \\
 &= -\lambda^3 + 3\lambda + 2 \\
 &= (\lambda+1)(-\lambda^2 + \lambda + 2) \\
 &= (\lambda+1)(\lambda+1)(\lambda-2) \Rightarrow \lambda_1 = -1 \text{ (multiplicity 2)}, \lambda_2 = 2
 \end{aligned}$$

Eigenvectors

$\lambda_1 = -1$ Solve $(A + I)\vec{v} = \vec{0}$

$$\begin{pmatrix} 6 & -6 & 3 \\ 6 & -6 & 3 \\ 6 & -6 & 3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 6 & -6 & 3 \\ 6 & -6 & 3 \\ 6 & -6 & 3 \end{pmatrix} \xrightarrow[r_3 \rightarrow r_3 - r_1]{r_2 \rightarrow r_2 - r_1} \begin{pmatrix} 6 & -6 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{aligned} 6v_1 - 6v_2 + 3v_3 &= 0 \\ v_1 &= v_2 - \frac{1}{2}v_3 \end{aligned}$$

v_2, v_3 arbitrary, so let $v_2 = s, v_3 = t$
 $\Rightarrow v_1 = s - \frac{1}{2}t$

$$\Rightarrow \vec{v} = \begin{pmatrix} s - \frac{1}{2}t \\ s \\ t \end{pmatrix} = s \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda_1 = -1, \text{ basis for eigenspace} = \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} \right\}$$

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 read

$\lambda_2 = 2$ Solve $(A - 2I)\vec{v} = \vec{0}$

$$\begin{pmatrix} 3 & -6 & 3 \\ 6 & -9 & 3 \\ 6 & -6 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 3 & -6 & 3 \\ 6 & -9 & 3 \\ 6 & -6 & 0 \end{pmatrix} \xrightarrow{\substack{r_2 \rightarrow r_2 - 2r_1 \\ r_3 \rightarrow r_3 - 2r_1}} \begin{pmatrix} 3 & -6 & 3 \\ 0 & 3 & -3 \\ 0 & 6 & -6 \end{pmatrix} \xrightarrow{r_3 \rightarrow r_3 - 2r_2} \begin{pmatrix} 3 & -6 & 3 \\ 0 & 3 & -3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$3v_1 - 6v_2 + 3v_3 = 0 \Rightarrow v_1 = 2v_2 - v_3$$

$$3v_2 - 3v_3 = 0 \Rightarrow v_2 = v_3$$

So, $\vec{v} = \begin{pmatrix} t \\ t \\ t \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow \lambda_2 = 2, \vec{v} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$
(Note: The original text says "v3 arbitrary, so let v3 = t -> v2 = t, v1 = t")

Section 7.1

1. $x'' + 3x' + 7x = t^2$

Let $x_1 = x$

$x_2 = x'$

Then $x_1' = x_2$. But $x_1' = x_2 \Rightarrow x_1' = x_2$

$$x_2' = x'' \text{. But, since } x'' + 3x' + 7x = t^2, x'' = -3x' - 7x + t^2$$

$$= -3x_2 - 7x_1 + t^2$$

$$\Rightarrow x_2' = -3x_2 - 7x_1 + t^2$$

So, $\begin{cases} x_1' = x_2 \\ x_2' = -7x_1 - 3x_2 + t^2 \end{cases}$

3. $t^2 x'' + t x' + (t^2 - 1)x = 0$

Let $x_1 = x$

$x_2 = x'$

Then $x_1' = x_2$

$x_2' = x''$

$$t^2 x'' + t x' + (t^2 - 1)x = 0 \Rightarrow x'' = -\frac{1}{t} x' - \frac{t^2 - 1}{t^2} x$$
$$= -\frac{1}{t} x_2 - \left(\frac{t^2 - 1}{t^2}\right) x_1$$

$$\text{So } \begin{cases} x_1' = x_2 \\ x_2' = -\frac{(t^2-1)}{t^2}x_1 - \frac{1}{t}x_2 \end{cases}$$

Section 7.2

3. $x' = -3y, y' = -3x$

$$\Rightarrow \begin{cases} x' = 0x - 3y \\ y' = -3x + 0y \end{cases} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix}' = \begin{pmatrix} 0 & -3 \\ -3 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \Rightarrow \vec{x}' = \begin{pmatrix} 0 & -3 \\ -3 & 0 \end{pmatrix} \vec{x}$$

6. $x' = tx - e^t y + \cos t, y' = e^{-t}x + t^2 y - \sin t$

$$\begin{cases} x' = tx - e^t y + \cos t \\ y' = e^{-t}x + t^2 y - \sin t \end{cases} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix}' = \begin{pmatrix} t & -e^t \\ e^{-t} & t^2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix}$$

$$\vec{x}' = \begin{pmatrix} t & -e^t \\ e^{-t} & t^2 \end{pmatrix} \vec{x} + \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix}$$

16. $\vec{x}' = \begin{pmatrix} 4 & 1 \\ -2 & 1 \end{pmatrix} \vec{x}, \vec{x}_1 = e^{3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \vec{x}_2 = e^{2t} \begin{pmatrix} 1 \\ -2 \end{pmatrix} \Rightarrow \vec{x}_1 = \begin{pmatrix} e^{3t} \\ -e^{3t} \end{pmatrix}, \vec{x}_2 = \begin{pmatrix} e^{2t} \\ -2e^{2t} \end{pmatrix}$

$$\vec{x}_1' = \begin{pmatrix} 3e^{3t} \\ -3e^{3t} \end{pmatrix}; \begin{pmatrix} 4 & 1 \\ -2 & 1 \end{pmatrix} \vec{x}_1 = \begin{pmatrix} 4 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} e^{3t} \\ -e^{3t} \end{pmatrix} = \begin{pmatrix} 4e^{3t} - e^{3t} \\ -2e^{3t} - e^{3t} \end{pmatrix} = \begin{pmatrix} 3e^{3t} \\ -3e^{3t} \end{pmatrix} = \vec{x}_1' \checkmark$$

$$\vec{x}_2' = \begin{pmatrix} 2e^{2t} \\ -4e^{2t} \end{pmatrix}; \begin{pmatrix} 4 & 1 \\ -2 & 1 \end{pmatrix} \vec{x}_2 = \begin{pmatrix} 4 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} e^{2t} \\ -2e^{2t} \end{pmatrix} = \begin{pmatrix} 4e^{2t} - 2e^{2t} \\ -2e^{2t} - 2e^{2t} \end{pmatrix} = \begin{pmatrix} 2e^{2t} \\ -4e^{2t} \end{pmatrix} = \vec{x}_2' \checkmark$$

$$W(\vec{x}_1, \vec{x}_2) = \begin{vmatrix} e^{3t} & e^{2t} \\ -e^{3t} & -2e^{2t} \end{vmatrix} = e^{3t}(-2e^{2t}) - (-e^{3t})e^{2t} = -2e^{5t} + e^{5t} = -e^{5t} \neq 0 \Rightarrow \{\vec{x}_1, \vec{x}_2\} \text{ lin. indep.}$$

$$\Rightarrow \vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 \Rightarrow \vec{x} = c_1 e^{3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

25. Find c_1, c_2 in #16. given $x_1(0) = 11, x_2(0) = -7$

$$\vec{x}(0) = \begin{pmatrix} x_1(0) \\ x_2(0) \end{pmatrix} = \begin{pmatrix} 11 \\ -7 \end{pmatrix} \Rightarrow \begin{pmatrix} 11 \\ -7 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$\Rightarrow \begin{cases} c_1 + c_2 = 11 \\ -c_1 - 2c_2 = -7 \end{cases} \Rightarrow \begin{cases} c_1 = 15 \\ c_2 = -4 \end{cases} \Rightarrow \vec{x}(t) = 15e^{3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} - 4e^{2t} \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$